Janus: A Multi-TCP Framework for Application-Aware Optimization in Mobile Networks

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Abstract—As the dominant protocol on the Internet, TCP has attracted significant attention and has been implemented in various ways, each of which optimizes for a single objective such as high throughput or low delay. However, in today’s mobile networks that carry traffic from diverse types of flows, this approach may lead to misconfiguration of TCP congestion control algorithms and further degrade performance for many applications. In this paper, we propose Janus, a new transport-layer framework that automatically selects among existing congestion control variants to optimize traffic in accordance with application demands. Janus is easy to deploy because it reuses existing, well-tested congestion control implementations, and does not require any in-network or client-side changes. To explore the potential for this approach, we implement Janus in the Linux kernel and extensively evaluate its performance with both emulated and real Internet traffic. We show Janus outperforms alternative protocols by offering fast convergence times in response to changing network conditions, achieving 5-10X lower delay with comparable or higher throughput. Our approach also significantly improves user-perceived performance according to QoE metrics, with up to 5X fewer interruptions for video streaming applications and 2X faster page loading for web-browsing applications.

Index Terms—TCP, congestion control, QoE, transport layer, mobile application.

1 INTRODUCTION

User-perceived quality of experience (QoE) is a key factor that influences customer satisfaction. This directly impacts the consumer’s preference for wireless service providers as well as the popularity of applications (apps) that run on smart-devices. Thus, a key challenge is how to meet QoE requirements for users continuously, given the tremendous diversity of apps and varying wireless bandwidth with mobility [1]. A variety of innovative congestion control protocols have been proposed for specific target scenarios to address these issues. Over 15 TCP variants are available in the latest Linux release [2], and the number is still growing. We argue that no single protocol can capture the collective needs of every possible app. In this work, we explore the effectiveness of automatically select and configure existing congestion control protocols to maximize the QoE based on the workload for each app that uses the network.

1.1 Motivation for Janus

Despite a large number of available options, only one congestion control protocol (usually chosen from either NewReno or Cubic on Linux) is active within the network protocol stack of a given server. This conservative choice was largely driven by two limitations of congestion control design:

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- Unknown last-mile wireless access link: Congestion control protocols are often designed for a specific network architecture and only work best in the scenario for which they were designed (see Sec. 2). Unfortunately for mobile networks, the choice of congestion control protocols is usually made at the server side, which is unaware of the actual last mile link condition at the client side. In today’s content delivery network (CDN) architecture, a single server may provide service to thousands of mobile users, but there may also be large diversity in the wireless access links that range from traditional WiFi/LTE to 60 GHz mmWave [3]. Therefore, in the absence of knowledge about client-side wireless access conditions, servers are typically configured to use a single, standard congestion control protocol, even though it may lead to suboptimal performance.

- Application-agnostic protocol selection: A key goal of a congestion control protocol is to share the bandwidth fairly...
among competing flows. However, this flow-level fairness ignores application-layer requirements and can result in inefficient resource allocation, or even drastically degrade QoE for an app when flows with conflicting demands compete for the network resources (See Sec. 3). Given this app-agnostic transport-layer design, some content providers focus on application layer enhancement approaches, e.g., YouTube incorporates adaptive bitrate (ABR) streaming to balance video quality and rebuffering rates. Google has deployed a new QUIC [4] protocol, which re-implements most of the transmission control functions in the application layer. However, such approaches require application-specific logic that are not always easy to port to new and emerging apps, and they can give rise to complex interactions between the application and transport layers [5].

Given the above limitations, we believe that the main issue is not the lack of alternative congestion control protocols best suited to different scenarios, but rather an automated mechanism to select the right one to maximize the QoE of the active apps on the client device. We design Janus to solve this problem: it is a new transport protocol selection and adaptation framework that enables automatic per-flow congestion control protocol selection and optimization according to the app requirements. As shown in Fig.1, Janus allows each app to specify its bandwidth requirement to provide the best-case QoE, and then selects the congestion control algorithm according to the so called just aggressive enough principle. This means that Janus will select an aggressive congestion control protocol only when the bandwidth requirement of the app is not met, and switch back to a conservative one otherwise. This improves overall network performance for two reasons. First it ensures that the QoE requirement of a given app is satisfied quickly, as long as there is enough bandwidth; second it prevents an app from being unnecessarily aggressive after its demand has been met, thus saving resources for other co-existing apps.

1.2 Design Parameters for Janus and Contributions

While the principles behind Janus are straightforward, we identified and addressed three key challenges to enable a flexible, efficient, and fair solution. The first challenge is how to capture the collective needs of various apps. Not all apps have specific bandwidth requirements. For example, delay sensitive apps (e.g., web browsing) need to minimize delay while some other apps may simply need to maximize the link utilization (e.g., file downloading). The second challenge is how to seamlessly switch between congestion control protocols for each flow, in a way that satisfies multiple apps that are sharing the network with heterogeneous requirements. This is the central problem that Janus needs to solve. Third, Janus must operate when available bandwidth is not sufficient to satisfy the aggregate requirements of all apps. In this case, a fairness principle must be formulated to share the limited bandwidth resources among competing flows.

This paper makes three main contributions:

- We present Janus, a new transport framework that automatically selects different protocols for each flow according to specific app requirements. In this paper, we mainly focus on two representative delay- and loss-based congestion control protocols (Vegas and Cubic) to illustrates the design of Janus. In addition, we show in Sec.7, how to extend Janus with more TCP variants.
- We propose an adaptation policy for selecting and switching congestion control protocols in a way that quickly satisfies app requirements. We also analytically prove that our approach can ensure max-min fairness allocation given limited bandwidth.
- We implement Janus in the Linux kernel and experimentally evaluate its performance with traffic from both emulation and real-world apps. We show Janus provides excellent QoE, relative to other approaches, for practical situations. For example, it reduces rebuffering rates by up to 5X for a video streaming app and reduces page load times by up to 2X for web-browsing apps. It also shortens the queuing latency by up to 10X over Cubic and 5X over PCC, while attaining comparable or higher throughput.

2 RELATED WORK

Many congestion control protocols [6]–[16], [18]–[28] have been proposed to optimize transport protocol performance. For example, Westwood+ [7] uses bandwidth estimation to increase TCP robustness with non-congestion packet loss in wireless networks; Hybla [6] scales cwnd faster in satellite networks with very long round-trip-delay (RTT); Cubic [12] modifies the classical additive increase, multiplicative decrease (AIMD) rule of TCP to quickly saturate the link in high bandwidth-delay product (BDP) networks. Table 1 summarizes the features of several existing congestion control protocols. However, these protocols do not adapt their congestion-control strategy as the network evolves over time, as the server is unable to estimate future last-mile wireless link selections.

Another line of work utilizes both the end-hosts’ and in-network knowledge to make better congestion control decisions. For example, FCP [29] combines end-point control and explicit router feedback. [30] further suggests using end-point congestion control, arbitrary rate control and in-network packet prioritization all together to achieve faster flow convergence. However, such protocols present a high barrier to deployment since they require simultaneous support from both end-hosts and intermediate network switches. In comparison, Janus requires only modification at the server side and is effective even in incremental deployment.

Several protocol designs focus on learning how to achieve constant, optimal performance, despite changes in the network conditions. The key idea is to directly search for actions (e.g., increase/decrease cwnd or sending rate) that can maximize objectives (e.g., maximize throughput and minimize delay). Remy [31], [32] uses off-line training to obtain the optimal mapping between network conditions and the cwnd adjusting function. In contrast, the performance oriented congestion control (PCC) protocol [33] uses online learning to find the sending rate that can maximize the value of a utility function according to the feedback from the receiver in real time. Similar to Janus, PCC allows apps to specify their performance preference (throughput or RTT).
by choosing a corresponding utility function. We compare Janus with PCC in Sec.8 and find Janus achieves better performance tradeoffs as it can support co-existing flows with unique or even conflicting requirements, while PCC can only optimize for a single, pre-selected performance metric.

Two recent efforts [34], [35] propose the concept of virtualized congestion control. The key idea is to translate one congestion control protocol into another by inspecting and modifying packet headers. One important goal of virtualized congestion control is to allow flows using different congestion control protocols (e.g., ECN vs. non-ECN) to share bandwidth fairly with each other. In contrast, Janus proposes a different approach of directly switching among congestion control variants, and is more flexible than protocol translation.

The closest work to Janus is OpenTCP [36], where TCP parameters are optimized and adaptively selected among existing TCP variants according to the explicit network information collected in a software defined network (SDN). However, despite the conceptual similarities, there are two key differences between OpenTCP and Janus: (1) OpenTCP works for an SDN environment that allows the controller to get the global view and control of all network traffic, while Janus is designed for mobile network and only requires modification at the server side; (2) While OpenTCP mentions the idea of selecting TCP variants, the actual switching logic and procedures are not introduced. Our work demonstrates that doing so is not trivial, and we present a detailed design of protocol switching algorithms, with an implementation and thorough consideration of the diverse QoE requirements of different apps.

### 3 Preliminary Results & Problem Definition

The traditional goal of TCP is to share bandwidth fairly among flows. However, the flow-level fairness overlooks the actual requirement of various apps. As a result, a flow may behave aggressively and degrade the performance for other flows even when its own QoE requirement has been satisfied. We illustrate the problem with following two examples.

- **Inefficient resource allocation:** To demonstrate the problem of inefficient bandwidth allocation in classical TCP, we set up a video stream proxy server and play two YouTube videos on separate laptops, which were connected to the same WiFi hotspot with 12 Mbps downlink bandwidth. The video content is the same, but each laptop uses a different resolution (720P and 1440P). Theoretically, the total bandwidth is high enough to play both videos together smoothly. However, we find the 1440P video suffers from frequent stalls, and waits for an unacceptably long 30% of the total video time for re-buffering. The reason is shown in Fig. 2: the 1440P video flow only gets half of total bandwidth (6 Mbps, which is smaller than the 1440P bitrate) as TCP tries to allocate bandwidth evenly among two flows, which results in re-buffering for the 1440P video (shown as gray bars).

- **Managing conflicting requirements in flows:** It is well known that TCP cannot deal with the situation when co-existing flows have conflicting requirements, e.g., when a delay-sensitive flow and bulk transfer flow are competing for the same bottleneck link. To show this effect, we fetch the top 1000 most popular websites [37] automatically and measure the average RTT with/without a long-lived file downloading flow. From Fig.4, we see that 90% of web browsing flows have average RTT less than 100 ms without the file downloading flow, but this number reduces to only 10% in the presence of cross-traffic. This situation arises from a combined effect of choosing a loss-based TCP (Cubic used in this experiment) and its inherent aggressive nature that attempts to saturate the bottleneck link and its queues.

- **Lack of awareness of app QoE:** The main reason for the

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**Table 1:** Different network environments, underlying assumption on link properties and corresponding selected TCP variants

<table>
<thead>
<tr>
<th>Networks</th>
<th>Underlying Assumptions</th>
<th>Congestion Control Protocols</th>
</tr>
</thead>
<tbody>
<tr>
<td>Satellite</td>
<td>Very long RTT</td>
<td>Hybla [6]</td>
</tr>
<tr>
<td>Wireless links</td>
<td>Frequent non-congestion packet loss</td>
<td>Westwood+ [7], Veno [8], Jersey [9]</td>
</tr>
<tr>
<td>Sensor Network</td>
<td>Ad-hoc topology, limited power and transmission range</td>
<td>ESRT [10], CODA [11]</td>
</tr>
<tr>
<td>Modern Internet</td>
<td>High bandwidth and delay</td>
<td>Cubic [12], HTCP [13], Yeah [14], BBR [15]</td>
</tr>
<tr>
<td>Cognitive Radio</td>
<td>Dynamic Bandwidth availability</td>
<td>TP-CRAHN [16], TFRC-CR [17], CogNet [18]</td>
</tr>
<tr>
<td>Data Center</td>
<td>In-cast topology, stringent latency constrain</td>
<td>DCTCP [19], TIMELY [20], HULL [21], D4 [22]</td>
</tr>
<tr>
<td>Cellular/WiFi</td>
<td>Highly varying network condition, Buffer-bloating</td>
<td>Sprout [23], CQIC [24], Verus [25]</td>
</tr>
</tbody>
</table>
The three main components of Janus: (1) metrics collection, which gathers data regarding network conditions and app requirements. (2) TCP switching engine, which chooses the appropriate TCP variant for each flow given the metrics collected to ensure that app’s objectives can be met; (3) performance enhancement, which tunes the default operation of the chosen TCP variant to further improve the performance.

4.1 Overview

At a high level, Janus works as follows: it checks the target rate $R$ of an outgoing flow during the connection establishment stage. For bandwidth-guarantee flows, $R$ simply represents the required bandwidth for the app to provide ideal QoE. We will introduce how to configure target rate later in Sec.7.2. If the flow is not associated with any target rate (e.g., bulk transfer or delay sensitive flow), Janus will first initialize one for the flow according to the current available bandwidth and then adjust it adaptively as network load varies (described in Sec.4.2).

Next, Janus continuously logs the throughput of the flow to detect whether the target rate has been satisfied. If so, Janus will select a conservative congestion control protocol to avoid overwhelming the network. Otherwise, Janus will choose an aggressive protocol to compete for more bandwidth until target rate is reached (Sec.4.3). Ideally, each flow should quickly converge its throughput to the target rate and then stay with the conservative TCP. However, selecting TCP variants naively cannot assure stable performance, especially when flows with distinct demands are sharing the bottleneck link. Therefore, Janus also uses proactive rate control to increase bandwidth sharing efficiency and tries to clear the bottleneck buffer during TCP switching to further minimize the queuing latency (Sec.4.4).

A key problem arises if the total network bandwidth is not enough to satisfy the requirements of all co-existing flows. This is common in mobile networks due to limited wireless capacity. To solve this problem, we develop an adaptive target rate adjustment algorithm to scale down each flow’s target rate temporarily until the network condition is recovered. By lowering down each flow’s expectation, Janus avoids the race to keep competing for bandwidth and allows the flows to converge to max-min fairness allocation under the limited resources. Sec. 5 and Sec. 6 introduces the algorithm and provides the theoretical analysis, respectively.

4.2 Metrics Collection

This component is responsible for: (1) measuring the network condition and flow performance; (2) reading or initializing target rate for each flow according to each apps’ objective. The output of metrics collection will be fed into following blocks as reference to choose appropriate congestion control protocols and further optimize performance.

- **Network measurement**: We use throughput $P$ and round-trip delay $RTT$ as the two key metrics that influence the choice made by Janus. We carefully smooth the collected sample values to capture the meaningful trends within the network and yet avoid rapid fluctuations as follows.
  - **Throughput $P$**: Janus first calculates the sample throughput $\overline{P}_{\text{tmp}}$ by dividing the bytes acknowledged in a time window by the window length. Then, an Exponential Weight...
Moving Average (EWMA) filter $P_{avg} = \xi * P_{smp} + (1-\xi) * P$ is applied for smoothing. Through empirical measurements, we have observed that the values of $\xi = 1/8$ and one RTT as time window are preferred choices for this smoothing step. This setting is also used in bandwidth estimation techniques in other protocols [7].

**RTT:** Janus reads the round trip delay sample $tp->srtt$ recorded in the TCP/IP stack of the Linux kernel. Note this $tp->srtt$ has been previously passed through EWMA filter with $\xi = 1/8$ by the Linux kernel before feeding into Janus. However, we find that $tp->srtt$ still suffers from rapid random fluctuations in wireless network. To accurately track the trends in RTT changes while filtering noise, we further pass the $tp->srtt$ into a min filter (by taking minimum $tp->srtt$ in a time window).

- **Target rate initialization:** For bandwidth guarantee flows, the target rate $R$ should be configured beforehand since it is decided by app’s throughput demand. Therefore, Janus can read $R$ directly during the connection establishment time.

Unlikely bandwidth guarantee flows, bulk transfer and delay sensitive flows do not have any specific bandwidth requirements. In this case, Janus starts a flow with TCP Vegas and waits for two additional RTTs after the slow start stage finishes. Then it initializes the target rate as the current measured instantaneous throughput ($R = P_{smp}$). Note that the slow start phase of Vegas is conservative, i.e., it finishes as soon as packets start accumulating in the network. The newly joined flow can only fill packets in an under-utilized link. Therefore, the current throughput represents the available bandwidth that the new joining flow can use. We choose to wait two RTTs because flow throughput needs a short duration to ramp up after slow start.

Allowing a new flow to utilize available bandwidth yields several benefits. It prevents new flows from starving any bandwidth guarantee flows. It ensures high link utilization for bulk transfer flows, since it makes sure all available bandwidth is utilized. Finally, it prevents a large number of packets from accumulating in the bottleneck buffer, thus reducing queuing latency for delay sensitive flows.

Available bandwidth may change due to varying network conditions such as load, link capacity, etc. Janus uses the target rate adjustment algorithm (described in Sec.5) to reactively tune the target rate for bulk transfer and delay sensitive flows so to match the varying available bandwidth.

4.3 TCP Switching Engine

Congestion control algorithms can be loosely categorized into delay-based and loss-based. Delay-based TCP is considered more conservative, as it interprets an increasing delay as a sign of congestion and slows the sending rate down accordingly. On the other hand, loss-based TCP is more aggressive, as it aims to saturate the bottleneck link until packets begin to drop because of buffer overflow. Therefore, loss-based TCP usually achieves higher link utilization at the cost of increased queuing delay, while delay-based TCP manages to keep queuing delay stable, though sometimes failing to attain high throughput.

Janus balances the advantages of these two congestion control strategies by switching between a (i) conservative stage (i.e., choosing the TCP Vegas [38]) and (ii) aggressive stage (i.e., choosing the TCP Cubic [12]) based on the measured throughput and the target rate from the metrics collection block. We choose these two protocols because Vegas is a classical delay-base congestion control protocol and Cubic is one of the default congestion control protocols in Linux. We also discuss how to extend Janus with other TCP variants in Sec.7.

The stage transition logic is demonstrated in Fig. 5: Janus enters the conservative stage and switches to Cubic whenever the target rate is satisfied, otherwise, it enters in the aggressive stage to compete for more bandwidth. While the switching basic logic is straightforward, we note:

1. To avoid rapid oscillation between two stages, Janus uses a protection parameter $\gamma$ that allows this switch to the aggressive stage only when $P_{avg} < (1-\gamma) * R$.

2. Janus uses sample throughput $P_{smp}$ instead of $P_{avg}$ to decide when to transit to the conservative stage for a new joining flows, before the first conservative stage. This is because the initial value of the $P_{avg}$ is zero when this flow starts, and it takes few RTTs for the smoothed $P_{avg}$ to ramp up until it captures the actual throughput. After the flow enters into the conservative stage, Janus initializes $P_{avg}$ to the current instantaneous throughput and uses $P_{avg}$ to decide the state transition.

An example demonstrating the two-stage transition algorithm is given in Fig.6. We set the bottleneck bandwidth to be 10 Mbps and start a flow with 8 Mbps target rate. When the flow just joins in the network, Janus starts with TCP Cubic (aggressive stage) to quickly grab bandwidth. After its target rate $R$ has been satisfied (around 0.7 s, $P_{smp} > R$), Janus switches to TCP Vegas (conservative stage) to keep queuing delay stable. During bursty cross-traffic (6 - 8 s), the throughput drops below $(1-\gamma) * R$ (because of EWMA smoothing, it takes about 1s for $P$ to drop down before cross-traffic leaves), Janus returns to the aggressive stage until its throughput recovers (around 10 s, $P_{avg} > R$).

From the Fig.6, we notice that Janus increases $cwnd$ faster than the cubic function during aggressive stage (in this example, $cwnd$ increases by 1.5X in eight RTTs). We find that this is because of an undocumented rule in Cubic’s Linux implementation which specifies that $cwnd$ is increased by 5% every RTT before the first packet loss. This highlights the need to carefully limit aggression in Janus to avoid starving competing flows. We further discuss the influence of the duration of the aggressive stage later in Sec. 5.

4.4 Performance Enhancement

While above simple TCP switching algorithm satisfies the requirement of a single flow, more complex situations may arise when flows with various demands are competing for one bottleneck link. In this section, we discuss the
enhancements to the basic Janus switching algorithm with two additional mechanisms that (i) speed up convergence and increase bandwidth allocation efficiency by performing proactive rate control, and (ii) minimize the self-inflicted queuing delay during state transition by clearing the bottleneck buffer.

- **Rate control**: Classical TCP constantly probes for available bandwidth and then shares it equally among concurrent flows. Janus increases the overall efficiency in bandwidth utilization by actively controlling the sending rate of bandwidth guarantee flows, thus preventing such flows from grabbing resources greater than their demands. This rate control is used in the first aggressive stage and the subsequent conservative stage. Janus does not modify the code of any existing congestion control algorithms; rather it limits the sending rate through (i) slow start threshold setting and (ii) maximum congestion window present in the Linux kernel.

  **Aggressive stage**: For a bandwidth guarantee flow, Janus initially chooses Cubic with the purpose of satisfying the target rate \( R \) as soon as possible. It overwrites the \( \text{snd\_sthresh} \) to \( R * D_p \), where \( D_p \) is the round-trip propagation delay (we introduce how to estimate \( D_p \) later in this section). Therefore, \( R * D_p \) is simply the number of outstanding packets required by the flow to reach its target rate. After \( \text{cwnd} \) reaches \( \text{snd\_sthresh} \), if the target rate is still not satisfied, Janus continues the normal congestion avoidance operation. By resetting the \( \text{snd\_sthresh} \), Janus significantly improves the convergence speed by making sure that the newly joined flow’s target rate can be reached as soon as possible, regardless of the end-to-end propagation delay of the connection.

  **Conservative stage**: During the conservative stage, Janus limits the throughput \( P \) of a bandwidth guarantee flow to \( (1 + \varepsilon) * R \), where \( \varepsilon \) decides the extra bandwidth potentially obtained by each flow. For this, Janus sets the maximum \( \text{cwnd} \) to \( (1 + \varepsilon) * R * \text{RTT} \) when \( P_{\text{avg}} > (1 + \varepsilon) * R \), and removes this limit when \( P_{\text{avg}} < R \). This ensures that the throughput of the bandwidth guarantee flow stays between \( R \) and \( (1 + \varepsilon) * R \), thus preventing the flow from trying to compete for more bandwidth than it demands.

- **Buffer clearing**: For delay sensitive apps, the goal of minimizing queuing delay cannot be achieved in isolation by a given end-device. This is because different flows may have accumulated packets in the network, making it impossible for other flows to further reduce delay. Therefore, Janus forces every flow to minimize the self-inflicted queuing delay. Unfortunately, following the aggressive stage, flows accumulate many packets in the bottleneck buffer. As Vegas can only reduce one outstanding packet in every RTT duration, it takes a while for Vegas to compensate for the increased queuing delay incurred during the aggressive stage (Fig. 6, 0.7–9 s). Furthermore, Vegas may regard the extra queuing delay as part of the link latency and not attempt to reduce outstanding packets at all (after 10 s).

  To solve this problem, Janus cuts the \( \text{cwnd} \) to \( P_{\text{avg}} * D_p \) every time before switching to the conservative stage so that the flow’s own outstanding packets is just large enough to maintain its current throughput. This allows the depletion of packets in the bottleneck buffer, thus minimizing the queuing latency during the transition.

- **Estimating propagation delay**: The success of both rate control and buffer clearing requires accurate estimation of propagation delay \( D_p \). Janus regards the minimum RTT observed \( (\text{base\_rtt}) \) during the connection lifetime as estimated propagation delay. However, it is well known that delay based TCP like Vegas suffers from the so called \( \text{re-routing} \) problem [39]. This happens when link latency varies because of changing routes or user mobility. To address this issue, Janus updates \( D_p \) when it enters a new conservative stage as:

\[
D_p = \text{RTT}_{\text{min}} - \frac{Q_{\text{avg}}}{P_{\text{avg}}}
\]

\( \text{RTT}_{\text{min}} \) is the minimum RTT sample taken at the start of a conservative stage. \( Q_{\text{avg}} \) is the average queued packets a conservative TCP will try to maintain in the bottleneck link buffer. Janus estimates \( D_p \) by subtracting \( \text{RTT}_{\text{min}} \) from \( \frac{Q_{\text{avg}}}{P_{\text{avg}}} \), where the latter is the extra delay caused by average queuing packets of a conservative TCP. As we show in Sec.8, this allows Janus to accurately track the propagation delay despite the varying link latency in a mobile network.

## 5 Adaptive Target Rate Adjustment

When the cumulative bandwidth demands of all active flows exceeds the available network capacity, one or more flows will stay in the aggressive stage because the required target rate cannot be satisfied. This starts a race to consume bandwidth that forces other flows to also switch to Cubic, leading to higher queuing delay and packet loss rate. In this section, we introduce an adaptive target rate adjusting algorithm to solve this problem. The key idea is that Janus intelligently lowers the target rate of the flows given the limited bandwidth so that network can still converge. We start with the goal of adjusting the target rate, then describe the algorithm and configuration of the parameters in detail.

### 5.1 Goal of target rate adjustment

Target rate adjusting aims to re-allocate the limited bandwidth to flows by striking a balance between efficiency and fairness. Janus uses the max-min fairness (MMF) allocation principle [40], which implies: (1) flows with lower demand...
Fig. 7: An example of target rate adjustment algorithm: The flow enters the aggressive stage at $t_1$, and reduces target rate twice at $t_2$ and $t_3$, respectively. Then it leaves the aggressive stage because its throughput exceeds the adjusted target rate. Finally, in the conservative stage the flow gradually recovers its throughput as well as target rate.

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5.2 Algorithm for adaptive target rate adjustment

A Janus flow tunes its own target rate using only local information with Alg.1. Intuitively, if a flow stays in aggressive stage for too long, and queuing delay is increased during this stage, then it implies that (1) the bottleneck link is saturated, and (2) the current bandwidth is not enough to support the flow's target rate. In this case, the flow should reduce its target rate. Otherwise, if a flow is in the conservative stage with increasing throughput, then the flow may raise its target rate as surplus bandwidth is available.

A rigorous proof of MMF allocation with Alg.1 is provided in Sec.6. Here we explain the key steps of the algorithm: Janus measures the time elapsed $\text{time}_\text{diff}$ since entering the aggressive stage (line 3). If the flow’s throughput recovers to its original target rate $R$ in interval $\Delta T$ ($\text{time}_\text{diff} < \Delta T$), Janus leaves the aggressive stage without reducing $R$. Otherwise, Janus checks whether the bottleneck link is saturated by evaluating if $\text{RTT} > \Delta T$ and $\text{rtt}_\text{diff} > \sigma(\text{RTT})$ then  

Algorithm 1: Adaptive Target Rate Adjusting

\begin{algorithm}
\begin{algorithmic}[1]
\State \textbf{Input:} $P$: throughput; $R$: original target rate
\State \textbf{Output:} $R'$: adjusted target rate
\State $R' = R$; $\Delta T = 0$; \textit{prev}_\text{adjust}_\text{time} = \text{Now time}; \textit{prev}_\text{rtt} = \text{RTT};$
\While {in aggressive stage}
\State $\text{time}_\text{diff} = \text{Now time} - \text{prev}_\text{adjust}_\text{time}$
\State $\text{rtt}_\text{diff} = \text{RTT} - \text{prev}_\text{rtt}$
\If { $\Delta T = 0$ }
\State $\Delta T = \tau \times \gamma \times \text{RTT}$
\Else
\State $\Delta T = 2 \times \text{RTT}$
\EndIf
\If { $\text{time}_\text{diff} > \Delta T$ and $\text{rtt}_\text{diff} > \sigma(\text{RTT})$ }
\State \textbf{if} $R' > R'(1 - \gamma)$ and $R' \neq R$ then 
\EndIf
\EndWhile
\State return $R'$
\end{algorithmic}
\end{algorithm}

the increase of $R'$ is upper bounded by its original target rate $R$. However, there is no such limitation for bulk transfer flows since its original target rate $R = 0$. This allows bulk transfer flows to keep increasing $R'$ until full utilization of the bandwidth. An example showing the entire process of reducing/recovering target rate is given in Fig.7.

Finally, the time interval $\Delta T$ greatly influences Janus’s performance. A large $\Delta T$ allows a flow to stay longer in the aggressive stage and may potentially degrade the performance of competing flows. On the other hand, a small $\Delta T$ may unnecessarily reduce the target rate. Hence, we set $\Delta T$ in an adaptive manner, where the first $\Delta T_1 = \tau \times \gamma \times \text{RTT}$ and the following $\Delta T_i = 2 \times \tau \times \text{RTT}$ ($i \geq 2$). Here $\tau$ is a scaling factor controlling the duration of $\Delta T_1$. We will discuss the ideal setting of $\tau$ in Sec.6 and Sec.7. If after $\Delta T_1$ the target rate is not yet satisfied, Janus reduces the interval to $2 \times \text{RTT}$. This avoids hurting the performance of other flows by forcing a departure from the aggressive stage as soon as possible.

6 Max-Min Convergence Analysis

In this section, we analytically prove that multiple Janus flows converge to MMF bandwidth allocation using the distributed target rate adjusting algorithm under assumptions of limited network bandwidth. We note that this proof is not limited to Vegas and Cubic; rather it holds true for general delay-based and loss-based congestion control protocols.

- Hypothesis statement: Consider $N$ Janus flows sharing a single bottleneck link with capacity $C$. Packets arriving at the bottleneck router are served using the first in first out (FIFO) principle. $\bar{R} = \{R_1...R_N\}$ is the target rate vector, where $R_i$ denotes the requested target rate for flow $i$. Assuming network capacity is less than the total demand of all flows, i.e., $(\sum_{i=1}^{N} R_i > C)$, Alg.1 results in MMF allocation of bandwidth.

We prove this hypothesis using a simplified version of Janus with only the conservative stage. We then extend the
analysis for the full-featured Janus, and show that the additional aggressive stage does not affect the MMF allocation.

6.1 Simplified Janus with only conservative stage

Consider the throughput vector $\bar{P} = \{P_1, ..., P_N\}$ and the target rate vector $\bar{R} = \{R'_1, ..., R'_N\}$ after the system converges, where $P_i$ and $R'_i$ are throughput and adjusted target rate of flow $i$, respectively. We start with a simplified Janus with only the conservative stage. Therefore, if a flow’s throughput drops below $(1 - \gamma) * R_i$, it will reset its target rate directly to $(1 - \gamma) * R_i$ without switching to TCP Cubic. Additionally, the rate control technique requires the flow to limit its throughput under $(1 + \varepsilon) * R_i$.

The proof of MMF allocation for Janus is based on the property that multiple delay-based flows converge to fair bandwidth allocation, which is a basic requirement for any congestion control protocol (e.g., see [39] for the proof for Vegas). Therefore, without considering rate control, each Janus flow converges to the fair share $C/N$ in a finite amount of time. However, $C/N$ may be larger then the actual target rates of some flows. Assume flow $i$ has target rate $R_i < C/N$. In this case, the rate control limits its rate to $(1 + \varepsilon) * R_i$. Then, other flows start to compete for the bandwidth spared by flow $i$. This process repeats until the remaining bandwidth can no longer be fairly distributed to meet the target rate of the left-over flows.

After the system converges, we separate flows into two different sets: $\Phi_1$ with satisfied demands and $\Phi_2$ that includes the rest. The throughput flows in these two sets are: $\forall i \in \Phi_1, P_i \in [R_i, (1 + \varepsilon) * R_i)$, $\forall j \in \Phi_2, P_j \in \left[\frac{C - \sum\bar{R}_i}{\parallel \Phi_2 \parallel}, \frac{C - \sum\bar{R}_i}{\parallel \Phi_2 \parallel} * R_i\right]$. Specifically, as $\varepsilon \to 0$, $\forall i \in \Phi_1, P_i \to R_i$; $\forall j \in \Phi_2, P_j \to \frac{C - \sum\bar{R}_i}{\parallel \Phi_2 \parallel} * R_i$.

Conversely, we can derive the target rate vector $R'$ from the throughput vector $P'$. Since the throughput of an unsatisfied flow must lie between $[(1 - \gamma) * R_i, R'_i/(1 - \gamma)]$ after the system converges, we have $\forall i \in \Phi_1, R'_i = R_i$; $\forall j \in \Phi_2, R'_j \in [(1 - \alpha) * P_j, P_j/(1 - \alpha)]$, where $P_j \to \frac{C - \sum\bar{R}_i}{\parallel \Phi_2 \parallel} * R_i$ as $\varepsilon \to 0$.

Intuitively, this means that (1) flows in $\Phi_1$ receive a share just equal to their demand, and hence, they maintain their original target rate; (2) flows in $\Phi_2$ get the fair share of the residual bandwidth but must reduce their target rate correspondingly. Also, since only flows with target rate less than fair share will be limited, we have $\forall i \in \Phi_1, \forall j \in \Phi_2, R_i < R_j$. As all three MMF principles are satisfied (Sec.5.1), the final bandwidth allocation must follow MMF.

6.2 Full-featured Janus

We now extend the analysis to show that the complete Janus protocol (with the aggressive stage) does not deviate from the MMF allocation. We first introduce following lemma:

**Lemma 1**: If the bottleneck link is fully utilized, full-featured Janus flows cannot leave the aggressive stage without reducing their target rate within $\Delta T_1$ if $\tau < \frac{1}{\alpha}$, $\alpha$ is the increment of cwnd in every RTT of the aggressive TCP.

**Proof**: We need to prove that a flow can only utilize residual bandwidth after needs of all flows have been considered, and it cannot steal bandwidth from competing flows during the aggressive stage. Assume flow $i$’s throughput drops to $P_i = (1 - \gamma) * R_i$. This triggers an aggressive stage and Janus switches to Cubic for flow $i$. As a result, flow $i$ can leave the aggressive stage without reducing target rate only if its throughput $P$ recovers back to $R_i$ within $\Delta T_1$. We prove that this is impossible if the bottleneck link is fully utilized.

Let $W'$ denote the flow $i$’s cwnd at the point of entering the aggressive stage, which results in $W' = P_i * RTT$. Since during the aggressive stage, cwnd is increased by a factor of $\alpha$ every RTT (Sec.4.3). So after $\Delta T_1$, cwnd increases to:

$$W' = W * (1 + \alpha) * \frac{\Delta T_1}{RTT} \quad (2)$$

Using Taylor expansion and ignoring higher-degree components, $W'$ simplifies to:

$$W' = W * (1 + \alpha * \frac{\Delta T_1}{RTT}) \quad (3)$$

Inserting $\Delta T_1 = \tau * \frac{\gamma}{1 - \gamma} * RTT$ (from Alg. 1), we get:

$$W' = W * (1 + \alpha * \frac{\gamma}{1 - \gamma}) \quad (4)$$

Therefore, if $\tau < \frac{1}{\alpha}$, then $W' < W/(1 - \gamma)$. Also, note that the current $RTT'$ is larger than $RTT$ because of the aggressive behavior of flow $i$. So, after $\Delta T_1$, the throughput of flow $i$ will be bounded by:

$$P_i' = W'/RTT' < \frac{W}{(1 - \gamma) * RTT} = \frac{P_i}{1 - \gamma}, \quad (5)$$

The main takeaway is that if we set $\tau$ less than the inverse of the increment cwnd every RTT during aggressive stage, then flow $i$’s throughput cannot increase to $P_i/(1 - \gamma) = R_i$. Thus, it leaves the aggressive stage without reducing target rate.

**Lemma 1** explains why the MMF allocation property is still valid. Only flows in $\Phi_2$ may potentially enter the aggressive stage because they have unsatisfied target rate and must compete for the residual bandwidth. However, **Lemma 1** indicates that they cannot maintain high target rate during the aggressive stage. At the end, their throughput and target rate will converge to the range specified in Sec. 6.1.

Finally, we point out that minimum target rate $R_{min}$ will influence the MMF bandwidth allocation. If a flow sets $R_{min}$ too large (e.g., equal with $R_i$), then it could maintain its own high target rate by forcing down other flows to stay within lower target rate. Therefore, $R_{min}$ should be small enough to ensure that the throughput of all flows can fall in the range specified by their MMF share. Specifically, $R_{min}$ must satisfy: $\forall j \in \Phi_2, R_{min} < P_j/(1 - \alpha)$, where $P_j \to \frac{C - \sum\bar{R}_i}{\parallel \Phi_2 \parallel} * R_i$ as $\varepsilon \to 0$ to maintain the MMF allocation.

7 JANUS IMPLEMENTATION

We implement Janus as an kernel module in the TCP/IP stack based on Linux 4.2.6. In this section, we briefly describe the high-level context for our implementation. We also discuss the parameter configuration and the extension to other congestion control protocols.
7.1 Implementation overview

Our implementation only requires minimum modification of the kernel (~20 lines of code). Once receiving a new packet, Janus reads the TCP socket information tcp_sock associated with current flow, and then feeds the tcp_sock into the metrics collections module to update the estimation of the throughput and RTT.

TCP switching is achieved by calling the tcp_set_congestion_control function defined in tcp_cong.cc without interrupting the active TCP connection. We modify the Linux kernel to allow Janus get access to this function by adding the latter into the exported kernel symbols. Janus automatically falls back to the default TCP (NewReno or Cubic) if the switching fails (e.g., the selected TCP does not exist in the current kernel).

- **Janus API**: Janus accepts the desired target rate \( R \) (and optional minimum target rate \( R_{\text{min}} \)) from the application layer as input and configures the congestion control protocols according to Sec. 4.3. As described in Sec.3, target rate represents the desired bandwidth for the app to provide satisfactory QoE to users, e.g., the target and minimum rate for watching 1080P@60fps YouTube video is 18 Mbps and 9 Mbps, respectively [41]. We add two socket options \( \text{SO\_TARGET\_RATE} \) and \( \text{SO\_MIN\_TARGET\_RATE} \) to the TCP/IP stack of Linux kernel so that \( R \) and \( R_{\text{min}} \) can be specified with the kernel function \( \text{setsockopt} \) at the time of instantiating a connection socket. We provide a config interface file to enable Janus to support unmodified apps seamlessly. In the config file, the tuple \( \langle \text{source port:R/R}_{\text{min}} \rangle \) can be specified and fed to Janus.

7.2 Parameter configuration

Janus requires 4 parameters to be configured: (1) \( \gamma, \varepsilon \): margin parameter of throughput used in TCP switching and rate control respectively; (3) \( Q_{\text{avg}} \): average queued packets maintained by conservative TCP, which is used in propagation delay estimation; (4) \( \tau \): the scaling parameter used in target rate adjusting.

- **Configure \( \gamma, \varepsilon \)**: These two parameters are protocol-independent, i.e., they do not vary with different selected TCP variants. We empirically set \( \gamma = 0.2 \) and \( \varepsilon = 0.1 \), which is also the default setting in following evaluation.

- **Configure \( Q_{\text{avg}} \)**: The conservative TCP usually maintains a certain number of packets in the bottleneck buffer to make sure the link is fully utilized. \( Q_{\text{avg}} \) is ideally set as the default queued packets of conservative TCP. For example, Vegas bounds the buffer size between 2 and 6 packets, so \( Q_{\text{avg}} \) is 4.

- **Configure \( \tau \)**: As we proved in Sec.6, the minimal setting of \( \tau \) should be \( \frac{1}{\alpha} \), where \( \alpha \) denotes the \( \text{cwnd} \) increment of every RTT with aggressive TCP. For example, we set \( \tau \) as 20 if Cubic is chosen since \( \text{cwnd} \) is increased by 5% every RTT during aggressive stage. Also, we recommend \( \tau = 20 \) when it is difficult to decide the accurate increment of \( \text{cwnd} \) for other TCP variants (as long as the selected TCP is less aggressive than Cubic). The main reason is that \( \tau \) balances the aggressiveness of Janus. The larger \( \tau \) is, the longer Janus stays in the aggressive stage, which can negatively influence other flows. However, setting \( \tau \) too small may force Janus to unnecessarily reduce the target rate. Setting \( \tau = 20 \) and \( \gamma = 0.2 \) means that Janus stays in aggressive stage for at least 5 RTTs before reducing the target rate.

7.3 Extension to other TCP variants

Janus supports other TCP implementations in the server kernel through a plug-and-play mode, beyond Vegas and Cubic, which were selected to illustrate its operation in this paper. We provide two additional examples of Janus with the widely used TCP NewReno (Janus-reno) [39] and H-TCP (Janus-htcp) [13], designed for high-speed and high-latency networks.

To show that Janus still converges with these new loss based TCP variants, we let two flows with target rate \( R = 12 \text{ Mbps} \) compete for the bottleneck link with 20 Mbps bandwidth. We use the default parameter settings as introduced in Sec.7.2 (\( \gamma = 0.2, \varepsilon = 0.1, Q_{\text{avg}} = 4 \) and \( \tau = 20 \)). As shown in Fig.8 and Fig.9, both Janus-reno and Janus-htcp adjust the target rate for each flow and converge to the fair share of the bandwidth. However, it takes longer for Janus-reno to converge because NewReno increases \( \text{cwnd} \) slower than H-TCP in the aggressive stage. Besides, note the conservative TCP (Vegas) did not allocate the bandwidth exactly in a fair share (10 - 20 seconds). However, Janus ensures the throughput of these two flows remains within the convergence range of \([1-(1+\gamma+\varepsilon)+R,(1+\gamma+\varepsilon)+R]\). In fact, when flow 2 drops out at 20 seconds (Fig.9), it quickly switches to H-TCP and gets back the fair share of the bandwidth within 2 seconds. This experiment not only shows that Janus can be easily extended to include more TCP variants, but also indicates that the Janus actually improves the stability and fairness over single TCP configurations.

8 Experimental Evaluation

We implement Janus and evaluate its performance on a testbed with traffic from emulated workloads as well as real world apps. We wish to show that Janus:
Fig. 10: Our experimental setup includes a local server that generates emulated traffic and a proxy used to redirect Internet traffic. The topology represents a typical dumbbell-like network where multiple flows compete for the same bottleneck link.

In addition, we show how Janus is robust against varying link latency and fair when competing with heterogeneous TCP flows in Sec.8.4 and Sec.8.5, respectively.  

Testbed description: As shown in Fig.10, our testbed contains a local server connected to a wireless gateway router (both running Linux Ubuntu 14.04) via a 1 Gbps Ethernet link. We use the Linux Traffic Controller tool [42] on the wireless gateway for controlling the bandwidth, link latency and buffer size. Thus the wireless link is the bottleneck of the connection between servers and clients. The experimental topology represents a classical dumbbell-like network that widely used in previous research [31], where multiple flows compete for the same bottleneck link.

We use four Android HTC Desire 610 phones running Android 4.4 and two Dell laptops running Ubuntu 14.04 as the clients. The server generates multiple flows for different end-clients through a traffic generator that we have developed. In addition, to study the effect of Janus on real-world apps, we deploy a proxy to redirect the Internet traffic from the remote app servers (such as YouTube and Chrome).

Competing protocols: In our evaluation, we mainly use Cubic as the base-line protocol as it is one of the most widely used congestion control protocols (e.g., Google also uses Cubic in QUIC at the time of writing). We also compare Janus with PCC [33]: a state-of-art performance oriented congestion control protocol that is built atop UDP. Similar to Janus, PCC also aims to satisfy app-specific demands by selecting different utility functions that optimize either throughput or RTT. However, the selection of the utility function is predefined and cannot be changed during runtime. In the following evaluation, we refer to the PCC with throughput maximization utility function as PCC-tp and RTT minimization as PCC-rtt.

8.1 Satisfying target rates for bandwidth guarantee flows

We first study the convergence of Janus under varying network loads and show that our protocol can satisfy the bandwidth demands for each flow quickly. Then we validate our model in Sec.6 by showing that the Janus flows converge to MMF allocation under limited bandwidth.

8.1.1 Convergence studies

We schedule four bandwidth guarantee flows with different target rates $R$ (10, 8, 6, 4 Mbps) that enter and leave the network successively, while limiting the bottleneck bandwidth to 25 Mbps. The connection RTT is 60 ms and the bottleneck link buffer size is 200 packets (same RTT and buffer size setting is used unless otherwise stated). We use the satisfaction degree as the performance metric, which is defined as received throughput divided by target rate ($P/R$). Intuitively, satisfaction degree $< 1$ means the flow demand has not yet been satisfied. In contrast, satisfaction degree larger than one means the flow has received a larger share than it needs, which is also undesirable as it may hurt the performance for competing flows. Note that for flows without specified bandwidth requirements (Cubic and PCC), the satisfaction degree is simply the received throughput divided by its fair share of total bandwidth.

As shown in Fig.11(a), Janus allows each flow to grab the needed bandwidth and reach the satisfaction degree if there is residual capacity. After the last flow comes in at 32 s, we see only flows 3 ($R = 6$ Mbps) and 4 ($R = 4$ Mbps) can be satisfied. Note the fair allocation for each flow is 6.25 Mbps. The adaptive target rate adjustment algorithm guarantees that only flows that request bandwidth less than their fair share can be satisfied given limited resources. By comparison, TCP Cubic (Fig.11(b)) tries to allocate bandwidth evenly among all the flows but suffers from longer convergence time (almost 20 seconds). Lastly, in PCC, the first flow takes over 70% of the total bandwidth, leaving only 30% for other flows (Fig.11(c)), thus lead to large deviation in the satisfaction degree.

8.1.2 Analytical model validation

To validate our model in Sec.6, we start the same four bandwidth guarantee flows sequentially with a synchronized departure at 60 s, and plot results for two different bottleneck bandwidths- 25 Mbps and 20 Mbps. Fig. 12 shows that the observed average throughput closely matches with the analytic MMF bandwidth (Sec. 6). We notice flows with target rate equal to the MMF share (e.g., 4 Mbps) have slightly higher throughput than the theoretical value. This is because Janus attempts to achieve an extra $\varepsilon \ast R$ bandwidth (Sec.4.4) after its target rate has been reached.

8.1.3 Comparison with Google’s TCP for YouTube

To demonstrate the QoE improvement for real-world apps, we play the same 5-minute YouTube video simultaneously at different resolutions (1080 P and 1440 P, with target rates 4 Mbps and 10 Mbps respectively). This represents the scenario of two bandwidth guarantee flows sharing one bottleneck link (15 Mbps). We count the number of buffering events, total rebuffering duration (seconds) and the start up latency (seconds) for the 1440 P flow with (1) Janus (2) Cubic, and (3) the default TCP protocol that Google runs on the origin server (we omit the 1080 P result here because there is no rebuffering observed). To ensure a fair comparison, we confirm that the extra round trip delay between the Google frontend and our video streaming proxy is less than 2 ms.
Table 3: The QoE metrics for 1440P YouTube video with Janus and alternative protocols.

<table>
<thead>
<tr>
<th>Protocol</th>
<th>Rebuffering number</th>
<th>Rebuffering duration</th>
<th>Startup latency</th>
</tr>
</thead>
<tbody>
<tr>
<td>Janus</td>
<td>6</td>
<td>4.2</td>
<td>3.6</td>
</tr>
<tr>
<td>Cubic</td>
<td>21 (3.5X)</td>
<td>31.9 (7.6X)</td>
<td>3.5 (0.98X)</td>
</tr>
<tr>
<td>Unmodified</td>
<td>12 (2X)</td>
<td>22.3 (5.3X)</td>
<td>2.7 (0.75X)</td>
</tr>
</tbody>
</table>

As shown in Table 3, Janus greatly improves the QoE for 1440 P video compared with Cubic and interestingly, even Google’s own default protocol. It achieves up to 5X reduction in number of rebuffering events and 7.6X lowering of the re-buffering duration. The improvement occurs when Janus allocates more bandwidth for the 1440 P flow with explicit target rate setting. Note that this does not sacrifice the QoE for 1080 P video since there is no rebuffering observed. This implies users can get satisfactory QoE by sharing bandwidth more efficiently, which is an important design criterion for Janus (Sec. 3).

Fig. 11: Convergence dynamics of satisfaction degree (throughput/target rate, ideal value is 1) for four flows with (a) Janus (b) Cubic and (c) PCC-tp. Janus allows flows to quickly grab bandwidth according to the target rate before the bottleneck link is saturated and achieves the fastest convergence time when compared with Cubic and PCC.

Fig. 12: Flows converge to MMF allocation with bandwidth 25 Mbps (left) and 20 Mbps (right).

Fig. 13: 95th percentile queuing delay of emulated web traffic (left) and average throughput for background traffic (right).

8.2 Minimize latency for delay-sensitive flows

In this section, we study the reduction in queuing latency for delay sensitive flows with Janus and its effects on QoE for web-browsing applications.

8.2.1 Reducing queuing latency

We emulate a web workload by sending short, bursty flows of 100 KB every two seconds. Meanwhile, we compare the 95th-percentile queuing delay for emulated web flows in presence of a background long lived flow with five protocol settings: Janus-12 (bandwidth guarantee flow with 12 Mbps target rate), Janus-0 (bulk transfer flow without any target rate), PCC-tp, PCC-rtt and Cubic. The bottleneck link bandwidth is set to 15 Mbps.

From Fig.13(left), we see that Janus achieves almost an order of magnitude lower queuing latency than that of Cubic. Additionally, this does not sacrifice the performance of background traffic as shown in Fig.13(right), where the target rate of bandwidth guarantee flow is satisfied and the bulk transfer flow achieves the over 90% of the link utilization. This indicates that Janus solves the conflicting requirements problem (see Sec. 3) by preventing bulk transfer flows from overwhelming the bottleneck buffer.

We now compare the performance of Janus and PCC. We find that PCC-rtt achieves almost the same queuing delay as Janus, but it does so by sacrificing the throughput of competing flows (as shown in Fig.13(right)). With PCC-rtt the background traffic utilizes only about 73% of the link capacity. In contrast, while PCC-tp achieves high throughput, the queuing delay is nearly 5X greater than that of Janus. In summary, PCC requires explicit tradeoffs between
throughput and RTT, while Janus can satisfy various QoE requirements for different apps simultaneously.

8.2.2 Improving page loading time

We use web browsing to demonstrate QoE improvement for delay-sensitive apps using Janus. We implement an Android app that opens websites and collects Page Response Time (PRT, defined as the time until client receives last byte of response from server) and Page Load Time (PLT, defined as the time until entire page is loaded) via the Navigation Timing API [43]. We then use a Janus proxy to host four websites (Google, Facebook, Wikipedia, Amazon), which represent different types of network services (search, social, wiki and shopping). We compared the average PRT and PLT in presence of a background traffic with the same protocol setting as in the previous experiment (except PCC, since PCC can only be used to serve self-generated traffic).

As shown in Fig.14, Janus achieves almost ideal PRT and PLT as if there is no background traffic. This is because Janus tries to minimize queuing latency, which directly lowers the PRT and PLT for web pages with small objects. By comparison, Cubic incurs large queues at the bottleneck link, and leads to more than 2X larger PRT and PLT.

8.3 Link utilization with bulk transfer flows

In Sec.8.2, we showed that Janus can ensure high link utilization for a single bulk transfer flow in the presence of short, delay-sensitive flows. We now study two more scenarios with: (1) a mixed environment of bulk-transfer and bandwidth-guarantee flows; (2) all bulk transfer flows competing for the same bottleneck link.

8.3.1 Mixed classes of flows

We first evaluate whether a bulk transfer flow can coexist fairly with bandwidth guarantee flows. As shown in Fig.15, after one bulk transfer flow fully saturates the bottleneck link, we start three bandwidth-guarantee flows ($R = 5$ Mbps) in succession. Note that the initial bulk transfer flow relinquishes bandwidth for the subsequent bandwidth-guarantee flows, until they reach fair share of the total bandwidth (from 20- to 40s). Moreover, after the latter flows leave the network, the bulk transfer flow fully saturates the link again. This validates that Janus automatically achieves fair yet efficient resource allocation on a need-basis.

8.3.2 All bulk transfer flows

Without a target rate, Janus should reduce to classical congestion control that fairly allocates bandwidth among all flows. To verify this, we start four bulk transfer flows that last for 60 seconds. We then measure the throughput deviation $\Delta Tp$, computed as the difference between the largest throughput and smallest throughput achieved by these four flows. Intuitively, $\Delta Tp$ should be small (ideally 0) if the flows converge fast to the even bandwidth allocation. We compare $\Delta Tp$ between alternative protocols (Fig.16) and show that Janus achieves better performance: the throughput deviation $\Delta Tp$ is about 45% less than that of Cubic. PCC has much larger deviation, as shown in Sec.8.1.

8.4 Robustness against varying link latency

Vegas does not perform well when the link delay changes during a connection (Sec.4.4). Since Janus also uses Vegas, we would like to evaluate if Janus will suffer from the same problem. This is important since link latencies vary frequently in a mobile network.

We start two Janus flows (target rate 10 Mbps) sharing a 20 Mbps bottleneck link, and increase the $D_p$ by 20ms (from 40 ms) every 20 seconds. Then we plot the real-time throughput of one flow in Fig. 17 (another flow shows nearly identical performance). While the throughput of the
flow first drops due to the increasing propagation delay, Janus quickly recovers its 10 Mbps bandwidth allocation. Repeating the same experiments with Vegas shows that both flows arestarved, just as the link latency starts to increase.

To explain the robustness of Janus, we plot the $cwnd$ variation and estimated propagation delay $D_p$ in Fig.18. Link latency increases trigger the following processes: First Janus switches to the aggressive stage and increases $cwnd$ exponentially when the flow throughput drops below the bound $R \times (1 - r)$. After flow throughput recovers back to $R$, Janus clears the queued packets by cutting $cwnd$ down to $P_{avg} \times D_p$ (Sec.4.4) before switching back to Vegas again. Here, the estimated $D_p$ is outdated, so Janus further reduces the $cwnd$ driving the throughput proportionately lower, which forces Janus into the aggressive stage. Finally, Janus updates its estimation of $D_p$, and the above cycle is repeated once again with updated $D_p$, allowing Janus to converge the $cwnd$ at a higher level.

8.5 Fairness with other TCP

To study whether Janus can co-exist with flows of other TCP variants, we consider competing Cubic flows. We start one Janus flow and a Cubic flow simultaneously and measure their respective average throughput. We see in Fig.20 that the throughput for Janus flows is within a small fraction of the Cubic flows, and $R_{min}$ approaches the fair share of total bandwidth. This implies that despite the fact that delay-based protocols cannot share bandwidth evenly with loss-based protocols given their inherent conservative behavior, the minimum target rate addresses this limitation for Janus flows. The key reason is that Janus adopts a tit-for-tat competition strategy: it will first lower its target rate, in an attempt to share resources with competing flows when the network is saturated. However if the competing flow

continually overwhelms the network, Janus is forced into aggressive stage to assure at least $R_{min}$ is satisfied.

To take a closer look at the dynamics of convergence with heterogeneous flows, we start two Janus flows ($R_{min} = 5$ Mbps) and two Cubic flows consecutively. As shown in Fig. 20, Janus maintains its throughput around 5 Mbps given the presence of Cubic flows, and increases back to 10 Mbps as soon as the Cubic flows leave the network. Thus, Janus can co-exist nicely with different congestion control protocols as long as the minimum target rate is satisfied.

9 CONCLUSION

Given the tremendous diversity of mobile apps and wireless access technologies, manually configuring the TCP network stack for each scenario is inflexible, error-prone and usually leads to suboptimal performance. Janus instead enables automatic, per-flow TCP selection and configuration. Our approach is lightweight and has a low barrier to deployment because (i) it does not need any modification to existing congestion control implementations, and (ii) it does not depend on feedback from lower layers or in-network devices. We showed, through theoretical analysis as well as a proof-of-concept system implementation, that Janus not only improves QoE for various apps by seamlessly switching between different congestion control variants, but also enforces max-min fairness bandwidth allocation among flows given limited network resources.

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